

Systems of singularly perturbed differential equations

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Model problem

Reaction-convection-diffusion:

$$-Eu'' + Bu' + Au = f \text{ in } (0, 1), \quad u(0) = u(1) = 0$$

with

$$|E| \ll \max\{|B|, |A|\}.$$

Model problem

scalar convection-diffusion

$$-\varepsilon u'' + bu' + au = f \quad \text{in } (0, 1), \quad u(0) = u(1) = 0$$

scalar reaction-diffusion

$$-\varepsilon^2 u'' + au = f \quad \text{in } (0, 1), \quad u(0) = u(1) = 0$$

with

$$0 < \varepsilon \ll 1.$$

Model problem

Convection-diffusion

$$-\varepsilon_1 u_1'' + b_{11} u_1' + \cdots + b_{1\ell} u_\ell' + a_{11} u_1 + \cdots + a_{1\ell} u_\ell = f_1$$

\vdots

$$-\varepsilon_\ell u_\ell'' + b_{\ell 1} u_1' + \cdots + b_{\ell \ell} u_\ell' + a_{\ell 1} u_1 + \cdots + a_{\ell \ell} u_\ell = f_\ell$$

short:

$$\mathcal{L}u := -\text{diag}(\varepsilon)u'' + Bu' + Au = f$$

O'Riordan, Stynes ($\ell = 2$) 2009 AdCM

L. 2009 SINUM

Roos 2011 AML

Model problem

Reaction-diffusion

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Madden, Stynes ($\ell = 2$) ... 2003 IMA J NA

L., Madden ($\ell = 2$) ... 2004 Computing

L., Madden 2003-2006 IMA J NA

Outline

- challenges of singularly perturbed problems
- What is a “singularly perturbed problem”?
- difficulties in their numerical treatment
- stability for scalar differential operators
 - maximum/comparison principles
 - stability, **Green's functions**
 - error analysis
- systems of reaction-diffusion [convection-diffusion] eq's
 - stability
 - error analysis

Difficulties

Character of differential equation changes when $\varepsilon \rightarrow 0$

- 2nd order \rightarrow 1st order or algebraic
- elliptic \rightarrow hyperbolic or algebraic

certain boundary conditions become **superfluous**

$$-Eu'' + Bu' + Au = f$$

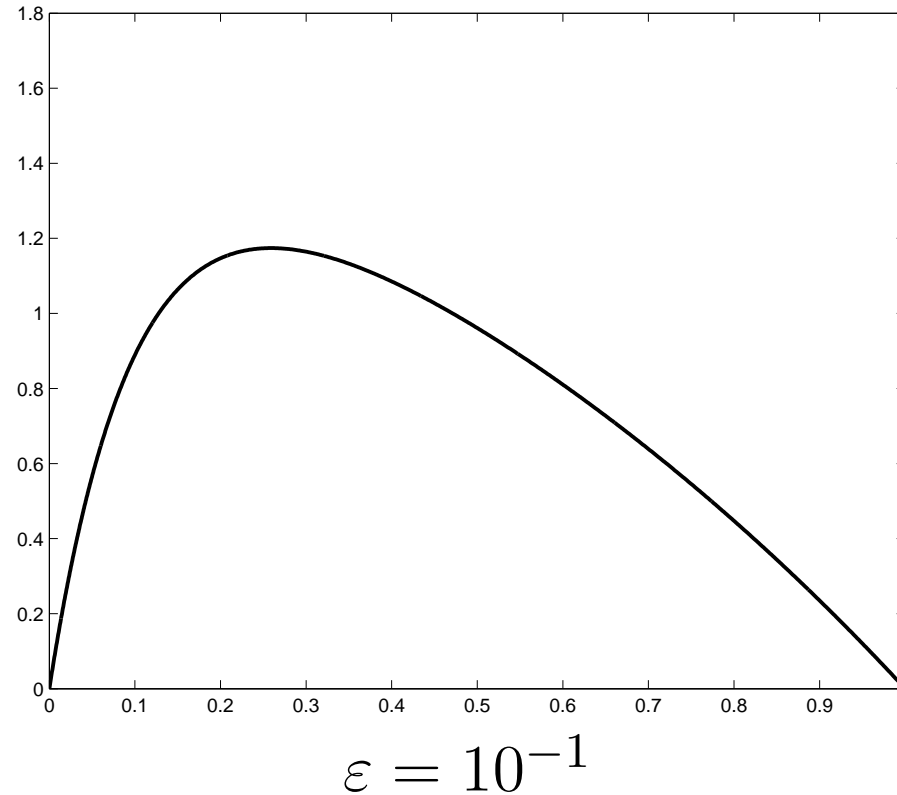
$$Bu' + Au = f$$

$$Au = f$$

Difficulties

Example:

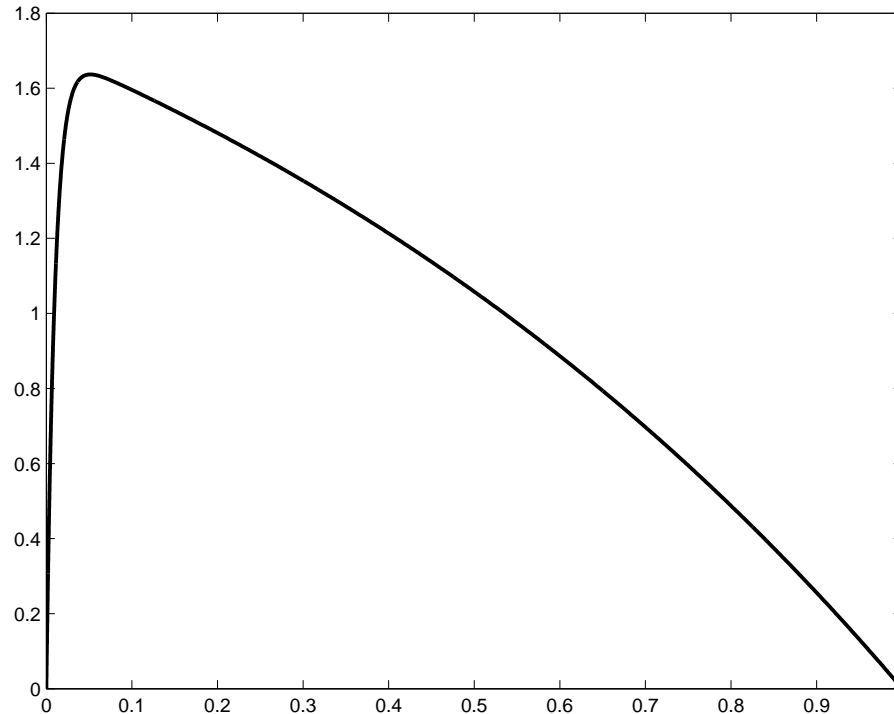
$$-\varepsilon u''(x) - u'(x) = e^x \text{ for } x \in (0, 1), \quad u(0) = u(1) = 0.$$



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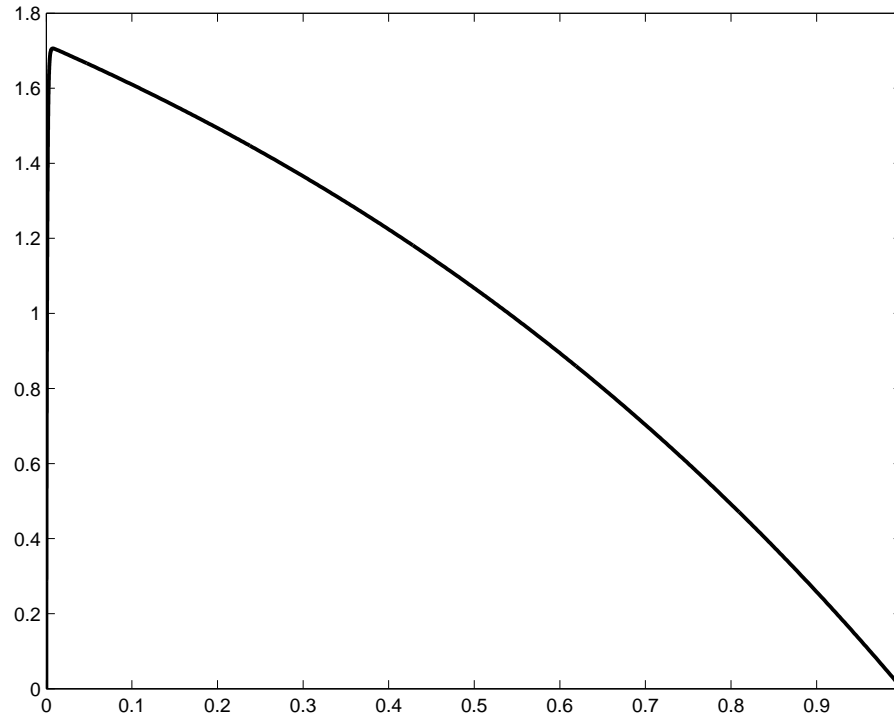


$$\varepsilon = 10^{-2}$$

Difficulties

Example:

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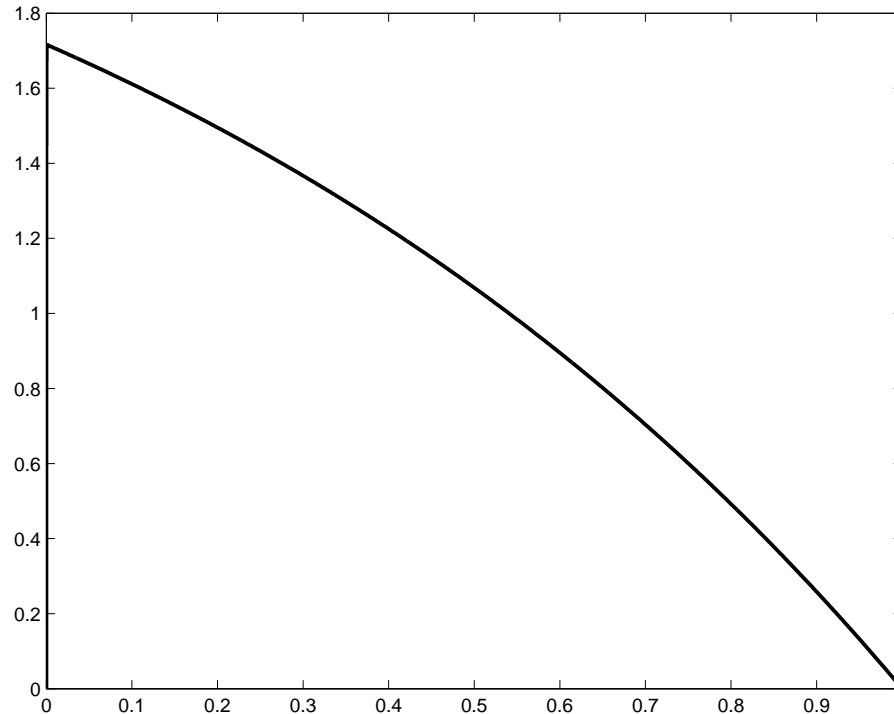


$$\varepsilon = 10^{-3}$$

Difficulties

Example:

$$-\varepsilon u''(x) - u'(x) = e^x \text{ for } x \in (0, 1), \quad u(0) = u(1) = 0.$$

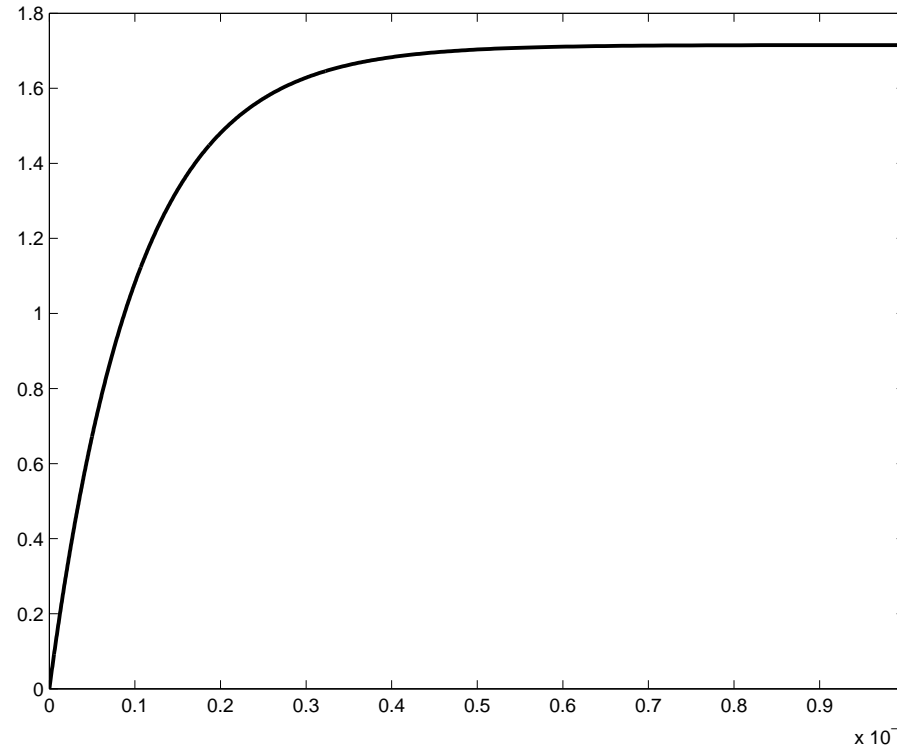


$$\varepsilon = 10^{-4}$$

Difficulties

Example:

$$-\varepsilon u''(x) - u'(x) = e^x \text{ for } x \in (0, 1), \quad u(0) = u(1) = 0.$$



$$\varepsilon = 10^{-4}$$

Difficulties

Discrepancy of

- prescribed boundary condition $u(0) = 0$ and
- solution u_{red} of reduced problem

$$-u'(x) = e^x \text{ for } x \in [0, 1), \quad u(1) = 0.$$

$$u_{red}(0) = e - 1 \approx 1.72$$

Consequence: solution **changes rapidly** near $x = 0$

\Rightarrow boundary **layer** $|u^{(k)}(0)| \sim \varepsilon^{-k}$

$$\varepsilon = 10^{-4}: \quad |u'(0)| \approx 10^4, \quad |u''(0)| \approx 10^8 \quad \text{etc}$$

Singularly perturbed problems

In example: $u : [0, 1] \times (0, 1] : (x, \varepsilon) \mapsto u(x, \varepsilon)$

$$\lim_{\varepsilon \rightarrow 0} \underbrace{\lim_{x \rightarrow 0} u(x, \varepsilon)}_{=0} = 0 \neq e - 1 = \lim_{x \rightarrow 0} \underbrace{\lim_{\varepsilon \rightarrow 0} u(x, \varepsilon)}_{=u_{red}(x)}.$$

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The solution of the boundary value problem possesses in $(x, \varepsilon) = (0, 0)$ a “classical” singularity.

In **any** neighbourhood of $(x, \varepsilon) = (0, 0)$ u attains **any** value between 0 and $e - 1 \approx 1.72$.

Singularly perturbed problems

Definition.

Let E and B be two normed spaces. Let $D \subset E$ be an open subset. The continuous function $u : D \rightarrow B, \varepsilon \mapsto u(\varepsilon)$ is said to be **regular** for $\varepsilon \rightarrow \varepsilon^* \in \partial D$ if there exists a function $u^* \in B$ with

$$\lim_{\varepsilon \rightarrow \varepsilon^*} \|u(\varepsilon) - u^*\|_B = 0;$$

otherwise $u(\varepsilon)$ is said to be **singular** for $\varepsilon \rightarrow \varepsilon^*$.

A problem $(\mathcal{P}_\varepsilon)$ with solution $u(\varepsilon) \in B, \varepsilon \in D$, is said to be **singularly perturbed** for $\varepsilon \rightarrow \varepsilon^* \in \partial D$ in the **norm** $\|\cdot\|_B$, if u is singular for $\varepsilon \rightarrow \varepsilon^*$.

Here: $E = \mathbb{R}, D = (0, 1], B = C[0, 1], \varepsilon^* = 0$

Numerical approximation

Standard difference discretization.

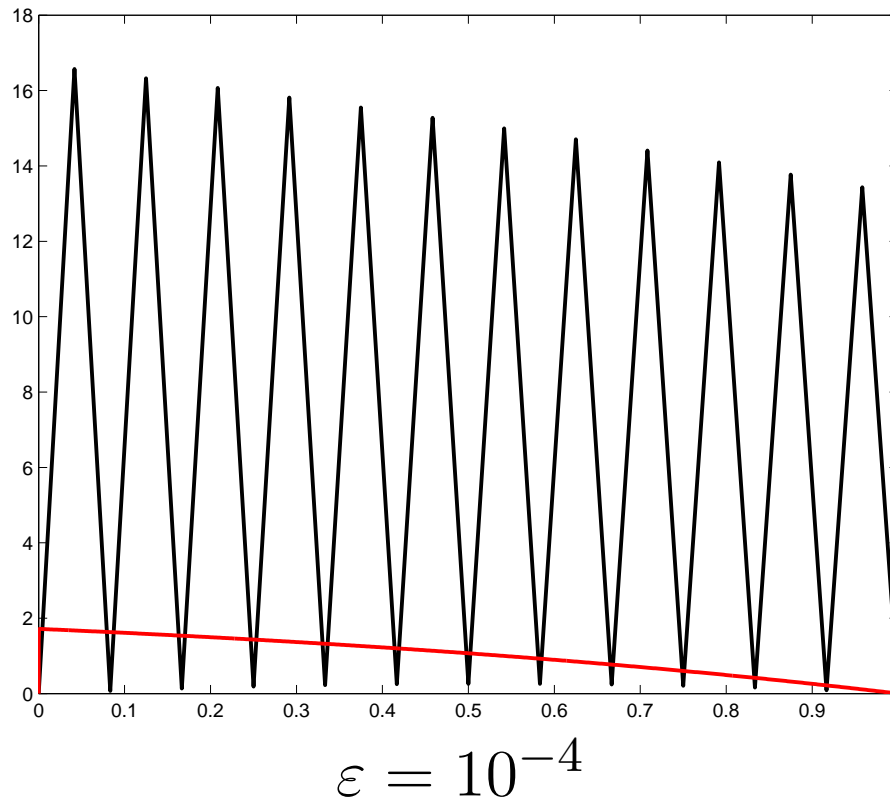
mesh $\omega : x_i = ih, h = 1/N, u_i^N \approx u(x_i)$

$$-\frac{\varepsilon}{h} \left(\frac{u_{i+1}^N - u_i^N}{h} - \frac{u_i^N - u_{i-1}^N}{h} \right) - b(x_i) \frac{u_{i+1}^N - u_{i-1}^N}{2h} = f(x_i)$$

Numerical approximation

Standard difference discretization.

mesh $\omega : x_i = ih, h = 1/N, u_i^N \approx u(x_i)$



Difference operator does **not** reflect stability properties of the **differential** operator.

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Numerical approximation

Upwind difference scheme. (stabilized)

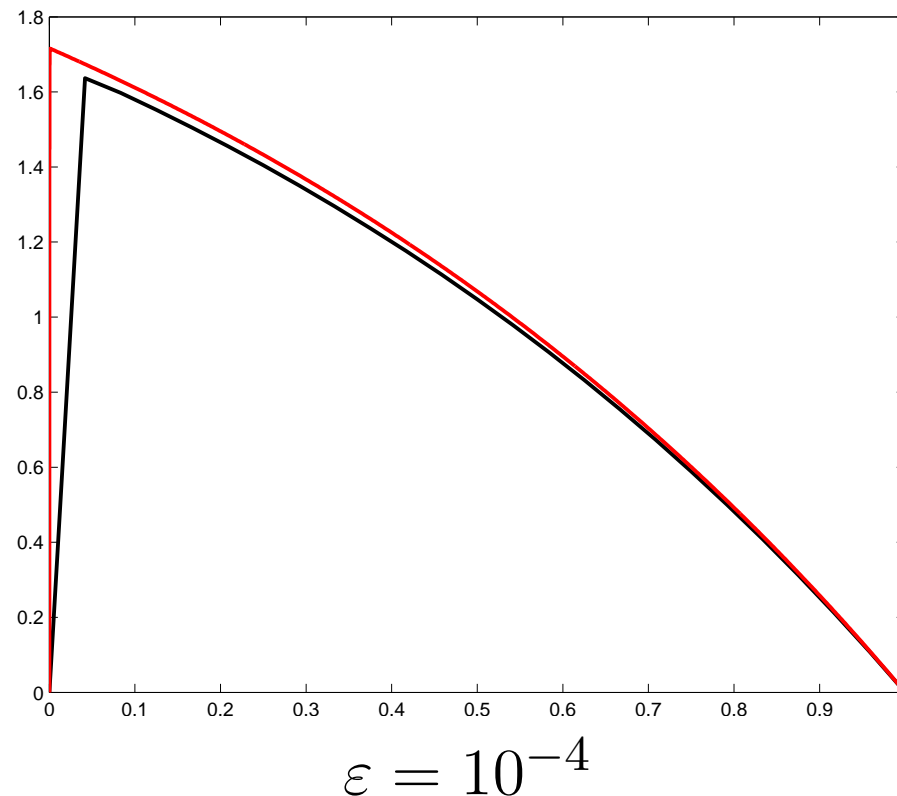
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Numerical approximation

Upwind difference scheme. (stabilized)

mesh $\omega : x_i = ih, h = 1/N, u_i^N \approx u(x_i)$



Stability: :-)

Resolution of layer: $\varepsilon \sim h = N^{-1}$:-)

Numerical approximation

Typical error estimate:

$$\|u - u^N\| \leq Kh, \quad \text{but } K \sim \|u'\| \sim 1/\varepsilon$$

Good approximations only when $h \ll \varepsilon$, i.e., $N \gg \varepsilon^{-1}$

Numerical approximation

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Two requirements

- Stability (upwind schemes)
- Resolution of layer (layer-resolving meshes)

Aim

- Applications: **robust/uniform** numerical methods

$$\| \mathbf{u}_\varepsilon - \mathbf{u}_\varepsilon^N \| \leq \vartheta(N)$$

where

N number of mesh points

$\lim_{N \rightarrow \infty} \vartheta(N) = 0$ convergence

$\partial_{\varepsilon_k} \vartheta = 0$ **robustness/uniformity**

$\| \cdot \|$ a reasonable norm

- Mathematics: analytical properties
 - stability (of continuous and discrete operators)
 - layer structure (derivatives, dependence on ε)
 - nice, elegant and easy to communicate theory

Stability of differential operators

$$(\mathcal{L}v)(x) := -\mu v''(x) + b(x)v'(x) + a(x)v(x), \quad \mu > 0$$

Theorem. (Maximum principle)

Assume there exists a function $\psi \in C^2(0, 1) \cap C[0, 1]$ with

$$\psi > 0 \text{ on } [0, 1] \quad \text{and} \quad \mathcal{L}\psi > 0 \text{ in } (0, 1).$$

Then for $u \in C^2(0, 1) \cap C[0, 1]$

$$\left. \begin{array}{l} \mathcal{L}u \geq 0, \quad \text{in } (0, 1) \\ u(0) \geq 0, \\ u(1) \geq 0 \end{array} \right\} \implies u \geq 0, \quad \text{on } [0, 1].$$

Proof. By contradiction, consider v defined by $\psi v = u$.

Stability of differential operators

Corollary. (Comparison principle)

Assume there exists a function $\psi \in C^2(0, 1) \cap C[0, 1]$ with

$$\psi > 0 \text{ on } [0, 1] \quad \text{and} \quad \mathcal{L}\psi > 0 \text{ in } (0, 1).$$

Then for any two functions $u, w \in C^2(0, 1) \cap C[0, 1]$

$$\left. \begin{array}{l} \mathcal{L}u \geq \mathcal{L}w, \text{ in } (0, 1) \\ u(0) \geq w(0), \\ u(1) \geq w(1) \end{array} \right\} \implies u \geq w, \text{ on } [0, 1].$$

The operator \mathcal{L} is said to be **inverse monotone**.

$\mathcal{L}u = f + \text{bcs}$ possesses a unique solution

Stability of differential operators

Green's function. Given u with $u(0) = u(1) = 0$. Then

$$u(x) = \int_0^1 \mathcal{G}(x, \xi) \underbrace{(\mathcal{L}u)(\xi)}_{f(\xi)} d\xi$$

inverse monotonicity $\iff \mathcal{G}(\cdot, \cdot) \geq 0$

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inverse monotonicity $\iff \mathcal{G}(\cdot, \cdot) \geq 0$

Characterization of \mathcal{G} .

$$(\mathcal{L}\mathcal{G}(\cdot, \xi))(x) = \delta(x - \xi) \quad (\mathcal{L}^*\mathcal{G}(x, \cdot))(\xi) = \delta(\xi - x)$$

Stability of differential operators

Green's function

$$u(x) = \int_0^1 \mathcal{G}(x, \xi) (\mathcal{L}u)(\xi) d\xi$$

Stability: Cauchy-Schwarz, Hölder, integration by parts

$$\|u\|_A \leq C \|\mathcal{L}u\|_B$$

For example

$$\|\mathcal{G}(x, \cdot)\|_{L_1} \leq C \implies \|u\|_\infty \leq C \|\mathcal{L}u\|_\infty$$

$$\|\mathcal{G}(x, \cdot)\|_\infty \leq C \implies \|u\|_\infty \leq C \|\mathcal{L}u\|_{L_1}$$

$$\|\mathcal{G}(x, \cdot)\|_{W^{1,1}} \leq C \implies \|u\|_\infty \leq C \|\mathcal{L}u\|_{W^{-1,\infty}}$$

Stability of discrete operators

Discrete operators = matrices, $L = (l_{ij}) \in \mathbb{R}^{m,m}$

L is said to be **inverse monotone** if for any $u, w \in \mathbb{R}^m$

$$Lu \geq Lw \implies u \geq w$$

Equivalent:

$$L^{-1} \geq 0.$$

Green's function $G = (g_{ij})$:

$$u_i = \sum_{j=1}^m g_{ij} (Lu)_j$$

$$G = L^{-1}$$

Tool: M-matrix criterion

Error analysis

Differential equation

$$\mathcal{L}u = f \text{ in } (0, 1), \quad u(0) = u(1) = 0.$$

mesh $\omega : 0 = x_0 < x_1 < \dots < x_N = 1, \quad u_i^N \approx u(x_i)$

$$[L^N u^N]_i = f_i^N, \quad i = 1, \dots, N-1, \quad u_0^N = u_N^N = 0$$

A priori error estimate

$$L^N(u - u^N) = L^N u - f^N = \text{truncation error}$$

Stability of $L^N \implies$

$$\|u - u^N\|_{A,\omega} \leq C \|L^N u - f^N\|_{B,\omega}$$

Error analysis

Differential equation

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A posteriori error estimate

$$\mathcal{L}(u - u^N) = f - \mathcal{L}u^N = \text{residuum}$$

Stability of $\mathcal{L} \implies$

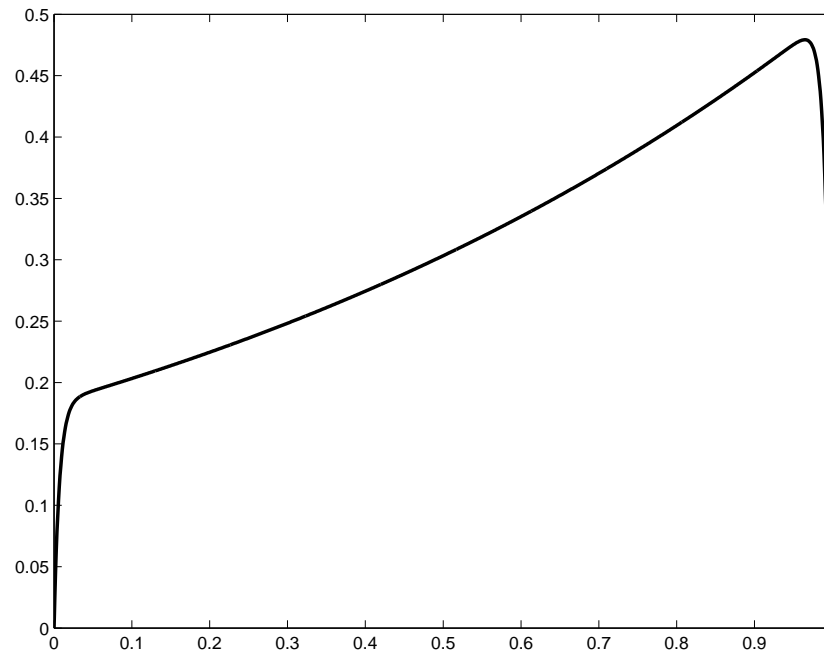
$$\|u - u^N\|_A \leq C \|f - \mathcal{L}u^N\|_B$$

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

Scalar reaction-diffusion

$$-\varepsilon^2 u'' + au = f \quad \text{in } (0, 1), \quad u(0) = u(1) = 0,$$

$$a(x) \geq \alpha^2, \quad x \in [0, 1], \quad \alpha > 0.$$



$$-10^{-3}u''(x) + 2u(x) = e^{x-1}$$

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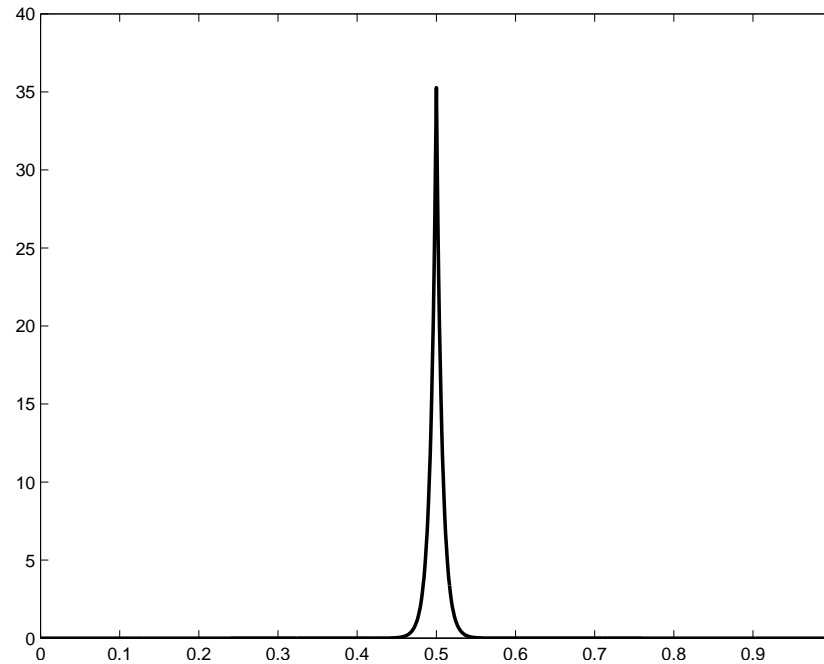
$$a(x) \geq \alpha^2, \quad x \in [0, 1], \quad \alpha > 0.$$

Derivative bounds

$$\left| u^{(k)}(x) \right| \leq C \left\{ 1 + \varepsilon^{-k} e^{-\alpha x/\varepsilon} + \varepsilon^{-k} e^{-\alpha(1-x)/\varepsilon} \right\}$$

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

Green's function: $\mathcal{G} := \mathcal{G}(x, \cdot)$



$$\mathcal{G} \geq 0, \quad \int_0^1 a(\xi)\mathcal{G}(\xi)d\xi \leq 1, \quad \int_0^1 |\mathcal{G}'(\xi)| d\xi \leq \frac{1}{\varepsilon\alpha},$$
$$\int_0^1 |\mathcal{G}''(\xi)| d\xi \leq \frac{2}{\varepsilon^2}.$$

Reaction-diffusion – $\text{diag}(\varepsilon^2)u'' + Au = f$

Stability

$$u(x) = \int_0^1 a(\xi) \mathcal{G}(\xi) \frac{(\mathcal{L}u)(\xi)}{a(\xi)} d\xi$$

$$|u(x)| \leq \left\| \frac{\mathcal{L}u}{a} \right\|_{\infty} \underbrace{\int_0^1 a(\xi) \mathcal{G}(\xi) d\xi}_{\leq 1}$$

$$\|u\|_{\infty} \leq \left\| \frac{\mathcal{L}u}{a} \right\|_{\infty}$$

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

Systems.

[L., Madden 2006]

- **essential assumption:** $a_{kk}(x) > 0$ for $x \in [0, 1]$
- for simplicity: two equations
- for simplicity: homogenous Dirichlet bc's

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

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Rewrite system

$$-\varepsilon_1^2 u_1'' + a_{11}u_1 = f_1 - a_{12}u_2$$

$$-\varepsilon_2^2 u_2'' + a_{22}u_2 = f_2 - a_{21}u_1$$

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

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... and use scalar stability!

Reaction-diffusion $-\text{diag}(\varepsilon^2)u'' + Au = f$

Hence — with $\| \cdot \| := \| \cdot \|_\infty$ —

$$\|u_1\| \leq \left\| \frac{f_1 - a_{12}u_2}{a_{11}} \right\| \leq \left\| \frac{f_1}{a_{11}} \right\| + \left\| \frac{a_{12}}{a_{11}} \right\| \|u_2\|$$

$$\|u_2\| \leq \left\| \frac{f_2 - a_{21}u_1}{a_{22}} \right\| \leq \left\| \frac{f_2}{a_{22}} \right\| + \left\| \frac{a_{21}}{a_{22}} \right\| \|u_1\|$$

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Rearrange

$$\underbrace{\begin{pmatrix} 1 & -\|a_{12}/a_{11}\| \\ -\|a_{21}/a_{22}\| & 1 \end{pmatrix}}_{\text{inverse monotone?}} \begin{pmatrix} \|u_1\| \\ \|u_2\| \end{pmatrix} \leq \begin{pmatrix} \|f_1/a_{11}\| \\ \|f_2/a_{22}\| \end{pmatrix}$$

inverse monotone?

Reaction-diffusion – $\text{diag}(\varepsilon^2)u'' + Au = f$

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inverse monotone?

took me 3 years...

Reaction-diffusion – $\text{diag}(\varepsilon^2)u'' + Au = f$

Theorem. Assume

• $a_{kk}(x) > 0$ for $x \in [0, 1]$

•
$$\Gamma := \begin{pmatrix} 1 & -\|a_{12}/a_{11}\| & \cdots & -\|a_{1\ell}/a_{11}\| \\ -\|a_{21}/a_{22}\| & 1 & \cdots & -\|a_{2\ell}/a_{22}\| \\ \vdots & \vdots & \ddots & \vdots \\ -\|a_{\ell 1}/a_{\ell\ell}\| & -\|a_{\ell 2}/a_{\ell\ell}\| & \cdots & 1 \end{pmatrix}$$

is inverse monotone.

Then

$$\max_{k=1,\dots,\ell} \|u_k\| \leq C \max_{k=1,\dots,\ell} \|f_k/a_{kk}\|.$$

... 2D, 3D.

Reaction-diffusion – $\text{diag}(\varepsilon^2)u'' + Au = f$

When is Γ inverse monotone?

- A is strongly diagonally dominant:

$$a_{kk}(x) > \sum_{i \neq k} |a_{ki}(x)| \quad \text{for } x \in [0, 1]$$

\implies M-criterion with $e \equiv 1$

- other cases..., for example

$$A = \begin{pmatrix} 1 & -47.11 \\ 0 & 1 \end{pmatrix}$$

- Compute Γ exactly/approximately and check sign pattern of Γ^{-1} [and magnitude of entries].

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

Error analysis.

Discretization: central differencing

$$\mathbf{L}^N \mathbf{u}_i^N = -\text{diag}(\varepsilon^2) \delta^2 \mathbf{u}_i^N + \mathbf{A}(x_i) \mathbf{u}_i^N = \mathbf{f}(x_i) = \mathbf{f}^N \quad \text{on } \omega$$

scalar:

$$-\frac{2\varepsilon^2}{h_i + h_{i+1}} \left(\frac{u_{i+1}^N - u_i^N}{h_{i+1}} - \frac{u_i^N - u_{i-1}^N}{h_{i+1}} \right) + a(x_i) u_i^N = f(x_i)$$

Stability. [analogously to \mathcal{L}]

$$\max_{k=1, \dots, \ell} \|u_k^N\|_{\omega} \leq C \max_{k=1, \dots, \ell} \|f_k/a_{kk}\|_{\omega}.$$

Reaction-diffusion – $\text{diag}(\varepsilon^2)u'' + Au = f$

Error: $u - u^N$

Truncation error: $\tau := \mathbf{L}^N (u - u^N) = \mathbf{L}^N u - \mathbf{f}^N$

Decomposition: $\eta = \psi + \varphi$

$$-\varepsilon_1^2 \delta^2 \psi_1 + a_{11} \psi_1 = \tau_1 = \varepsilon_1^2 (u_1'' - \delta^2 u_1),$$

$$-\varepsilon_2^2 \delta^2 \psi_2 + a_{22} \psi_2 = \tau_2 = \varepsilon_2^2 (u_2'' - \delta^2 u_2),$$

and

$$-\varepsilon_1^2 \delta^2 \varphi_1 + a_{11} \varphi_1 = -a_{12} (u_2 - u_2^N),$$

$$-\varepsilon_2^2 \delta^2 \varphi_2 + a_{22} \varphi_2 = -a_{21} (u_1 - u_1^N)$$

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

Scalar stability:

$$\|\varphi_1\|_\omega \leq \|a_{12}/a_{11}\|_\omega \|u_2 - u_2^N\|_\omega$$

$$\|\varphi_2\|_\omega \leq \|a_{21}/a_{22}\|_\omega \|u_1 - u_1^N\|_\omega$$

Triangle inequality

$$\|u_1 - u_1^N\|_\omega \leq \|\psi_1\|_\omega + \|a_{12}/a_{11}\|_\omega \|u_2 - u_2^N\|_\omega$$

$$\|u_2 - u_2^N\|_\omega \leq \|\psi_2\|_\omega + \|a_{21}/a_{22}\|_\omega \|u_1 - u_1^N\|_\omega$$

... imitate stability trick

$$\max_{k=1,\dots,\ell} \|u_k - u_k^N\|_\omega \leq C \max_{k=1,\dots,\ell} \|\psi_k\|_\omega$$

Reaction-diffusion – $-\text{diag}(\varepsilon^2)u'' + Au = f$

The ψ_k are solutions of scalar equations...

Recycle known ideas for scalar problems:

- fancy barrier functions for the truncation error
- **Green's function representations** :-) :-)
- or your favourite technique

in order to obtain a **convergence result**.

... provided we have **bounds for the derivatives** of the exact solution to estimate the truncation error!

Here: One pair of layers per equation: $\exp(-\alpha x / \varepsilon_k)$

... 2D, 3D?

Convection-diffusion – $\text{diag}(\varepsilon)u'' + Bu' = f$

... with strong coupling

$$-\varepsilon_1 u_1'' + b_{11} u_1' + b_{12} u_2' = f_1$$

$$-\varepsilon_2 u_2'' + b_{21} u_1' + b_{22} u_2' = f_2$$

earlier idea:

$$-\varepsilon_1 u_1'' + b_{11} u_1' = f_1 - b_{12} u_2'$$

stability

$$\|u_1\| \leq C \|f_1 - b_{12} u_2'\| \quad \text{bad – does not fit}$$

Convection-diffusion – $\text{diag}(\varepsilon)u'' + Bu' = f$

Scalar problem:

$$-\mu u'' + bu' = f \quad \text{in } (0, 1), \quad u(0) = u(1) = 0$$

with $b \geq \beta > 0$ or $b \leq -\beta < 0$ in $[0, 1]$

Then – standard stability

$$\|u\| \leq \beta^{-1} \|f\|$$

and – Andreev & Kopteva (1996), Andreev (2000)

$$\|u\| \leq 2\beta^{-1} \min_{F:F'=f} \|F\|$$

Convection-diffusion – $\text{diag}(\varepsilon)u'' + Bu' = f$

System:

[L. 2009]

$$-\varepsilon_1 u_1'' + b_{11} u_1' + b_{12} u_2' = f_1$$

$$-\varepsilon_2 u_2'' + b_{22} u_2' + b_{21} u_1' = f_2$$

with $|b_{kk}(x)| \geq \beta_k > 0$ for $x \in [0, 1]$.

$$-\varepsilon_1 u_1'' + b_{11} u_1' = f_1 - b_{12} u_2'$$

$$-\varepsilon_2 u_2'' + b_{22} u_2' = f_2 - b_{21} u_1'$$

... use scalar stability!

Convection-diffusion – $\text{diag}(\varepsilon)u'' + Bu' = f$

$$\|u_1\| \leq \beta_1^{-1} \|f_1\| + 2\beta_1^{-1} \|b_{12}\| \|u_2\|$$

$$\|u_2\| \leq \beta_2^{-1} \|f_2\| + 2\beta_2^{-1} \|b_{21}\| \|u_1\|$$

Rearrange

$$\underbrace{\begin{pmatrix} 1 & -2\beta_1^{-1} \|b_{12}\| \\ -2\beta_2^{-1} \|b_{21}\| & 1 \end{pmatrix}}_{\text{inverse monotone?}} \begin{pmatrix} \|u_1\| \\ \|u_2\| \end{pmatrix} \leq \begin{pmatrix} \beta_1^{-1} \|f_1\| \\ \beta_2^{-1} \|f_2\| \end{pmatrix}$$

inverse monotone?

Convection-diffusion – $\text{diag}(\varepsilon)u'' + Bu' = f$

Theorem. Assume

• $|b_{kk}(x)| \geq \beta_k > 0$ for $x \in [0, 1]$

•
$$\Gamma := \begin{pmatrix} 1 & -2 \|b_{12}\| / \beta_1 & \cdots & -2 \|b_{1\ell}\| / \beta_1 \\ -2 \|b_{21}\| / \beta_2 & 1 & \cdots & -2 \|b_{2\ell}\| / \beta_2 \\ \vdots & \vdots & \ddots & \vdots \\ -2 \|b_{\ell 1}\| / \beta_\ell & -2 \|b_{\ell 2}\| / \beta_\ell & \cdots & 1 \end{pmatrix}$$

is inverse monotone.

Then

$$\max_{k=1,\dots,\ell} \|u_k\| \leq C \max_{k=1,\dots,\ell} \|f_k\| .$$

Convection-diffusion – $\text{diag}(\varepsilon)u'' + Bu' = f$

Error analysis for a stabilized formally first order method:

- decomposition of error
- imitate stability analysis
- reduce to scalar problems

Results:

$$\max_{k=1,\dots,\ell} \|u_k - u_k^N\|_\omega \leq C \max_{j=1,\dots,N} \int_{x_{j-1}}^{x_j} \left\{ 1 + \sum_{m=1}^{\ell} |u'_m(s)| \right\} ds$$

$$\max_{k=1,\dots,\ell} \|u_k - u_k^N\|_\omega \leq C \max_{j=1,\dots,N} h_j \left\{ 1 + \sum_{m=1}^{\ell} \frac{|u_{m,j}^N - u_{m,j-1}^N|}{h_j} \right\} ds$$

Convection-diffusion – $\text{diag}(\varepsilon)u'' + Bu' = f$

Open issues:

- derivative bounds
 - L_1 -bounds [L. 2009]

$$\int_0^1 |u'_m(s)| ds \leq C$$

⇒ existence of an optimal mesh

- pointwise bounds: first guess [L. 2009]

$$e^{-\beta_m x/\varepsilon} \quad \text{if} \quad b_{m,m} \geq \beta_m > 0, \quad \dots \text{wrong}$$

- pointwise bounds: eigenvalues of B [Roos 2011]
- 2D, 3D: available stability results not strong enough

Conclusions

A simple trick allows to extend stability results for scalar problems to systems of singularly perturbed equations.

Solved problems.

- stability for reaction-diffusion and 1D convection-diffusion
- derivative bounds for reac-diff and conv-diff in 1D (including a priori and a posteriori error bounds)

Conclusions

A simple trick allows to extend stability results for scalar problems to systems of singularly perturbed equations.

Open issues.

- derivative bounds for higher-dimensional problems (corners!!)
- **strong** stability inequalities for higher dimensional convection-diffusion

Conclusions

A simple trick allows to extend stability results for scalar problems to systems of singularly perturbed equations.

Survey paper.

- Linß & Stynes: *Numerical solution of systems of singularly perturbed differential equations*, Comput. Meth. Appl. Math., 2009

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... The End. Thank you!